# PCI-8102

## Advanced 2-axis Stepper & Servo Motion Control Card :•



## Features =

- 32-bit PCI bus, Rev. 2.2, 33MHz
- Pulse output rate up to 6.55MHz
- Pulse output options: OUT/DIR, CW/CCW
- 9 2-axis linear/circular interpolation
- Continuous interpolation
- Position/speed change on-the-fly
- 13 home return modes and auto home search
- Hardware position compare
- High speed position latch function
- Programmable acceleration and deceleration time
- Trapezoidal and S-curve velocity profiles
- Multi-axis, simultaneous start/stop
- Programmable interrupt sources
- Supports up to 12 cards in one system
- Hardware backlash compensator
- Softwares limit function
- On-board GPIO 16IN/16OUT (P2 Connector)
- Card index switch setting
- Hardware emergency input
- Security protection for user's program
- Easy interface to any stepping motors, AC or DC servo, linear or rotary motors which have pulse train input mode
- All digital inputs and outputs are 2500V<sub>RMS</sub> isolated
- Manual pulser input interface
- More than 100 thread safe API functions

# **Ordering Information**

PCI-8102	Advanced 2-axis stepper & servo motion control card
DIN-68M-J3A0	Termination board for Mitsubishi MR-J3-A servo amplifier with 68-pin SCSI-II connector
DIN-68M-J2A0	Termination board for Mitsubishi MR-J2S servo amplifier with 68-pin SCSI-II connector
DIN-68Y-SGII0	Termination board for Yaskawa Sigma II servo amplifier with 68-pin SCSI-II connector
DIN-68P-A40	Termination board for Panasonic MINAS A4 servo amplifier with 68-pin SCSI-II connector

### Introduction

#### Advanced 2-axis Motion Controller

ADLINK PCI-8102 is an advanced 2-axis motion control card. Compared with the PCI-8132/PCI-8134 series, PCI-8102 offers better linear and circular interpolated move and continuous contouring performanceideal for advanced pulse train motion control solutions and complicated motion and pick-and-place applications.

#### Velocity or Position Override

The PCI-8102 provides powerful position or speed changing function while axis is moving. After motion begins, target of speed or position can be changed on the fly at the user's program.

#### Linear & Circular Interpolation

The PCI-8102 provides 2-axis linear/circular interpolation.

#### **Continuous Contouring**

The pre-register architecture of PCI-8102 offers the feature to build the continuous interpolation function, ie, the 2nd motion may follow previous motion instantly without latency. Thus perfect velocity continuity can be established.

#### **Position Latch**

The latch function is to capture the instant counter value of one certain axis when the latch signal activates. The LTC channel is used to receive the latch pulse. The latch function is implemented with hardware.

#### Automatic Backlash Compensation

Whenever direction change is occurred, the PCI-8102 outputs backlash corrective pulses before sending commands. During interpolation mode, this function will be ineffective.

#### 13 Home Return Modes

To fit into various mechanical design and operating restrictions, the PCI-8102 provides 13 home moving modes for users to choose as their best convenience.

#### Simultaneously Start/Stop

By using software program or external input signal, the PCI-8102 can perform simultaneously start/stop function on multi-axis in one card or multi-axis in multi-card. Also, the simultaneously stop function is selectable to be active when some axes are abnormally stopped.

#### Hardware Emergency Input

The PCI-8102 provides hardware emergency control with the cable wiring. When the emergency button is pressed, it triggers this function and the motion controller will cease sending pulses. This function is ideal protection for system designers.

#### Security Protection

PCI-8102 offers hardware security protection for system designers' software.

# Specifications

Motion	SCSI type Connector			ctor	EXGND	1	23	DO0
Number of controllable axes: 2	VPP	1	35	VPP	EXCND	2	24	DO1
Pulse output rate: 0.01pps to 6.5Mpps	EXGND	2	36	EXGND	EXGND	2	24	DOT
Max. Acceleration rate 245Mpps <sup>2</sup>	OUTO	2	27		DIN0	3	25	DO2
Speed resolution: 16-bit	0010+	3	51	0011+	DIN1	4	26	DO3
Encoder input rate: 6.55MHz under 4 x AB phase @ 1M cable	OUT0-	4	38	OUT1-	DIN2	5	27	FXGND
Encoder counter resolution: 28-bit	DIR0+	5	39	DIR1+	Dinz	Ŭ	21	EXCINE
Positioning Range: -134, 217, 728 ~ +134, 217, 727 pulses (28-bit)	DIR0-	6	40	DIR1-	DIN3	6	28	EXGND
Counters x 4 for each axis		-		01/01/4	DIN4	7	29	DO4
Comparators x 5 for each axis	SVON0 41	(	41	SVONT	DIN5	8	30	DO5
Motion Interface I/O Signals	ERC0	8	42	ERC1	VDD	9	31	DO6
Motion Interface I/o Signals	ALM0	9	43	ALM1	EVOND			507
Position compare output pin. CMP	INP0	10	44	INP1	EXGND	10	32	DO7
All I/O pins are differential and 2500V <sub>RMS</sub> optically isolated		11	45		DIN6	11	33	DO8
Incremental encoder signals input pins: EA and EB	RDTU		40	RUTI	DIN7	12	34	DO9
Encoder index signal input: EZ	EA0+	12	46	EA1+	DIN8	13	35	EXGND
Mechanical limit switch signal input pins: ±EL, SD and ORG	EA0-	13	47	EA1-	Biito			
General DO nin: DO x 16 (P2 Connector)	EB0+	14	48	EB1+	DIN9	14	36	VDD
General DI pin: DI x 16 (P2 Connector)	500	45	10		DIN10	15	37	DO10
Pulser signal input: PA and PB	EB0-	15	49	EB1-	DIN11	16	38	DO11
Simultaneous Start/Stop Signal I/O Pins: STA and STP	EZ0+	16	50	EZ1+	EXGND	17	39	DO12
	EZ0-	17	51	EZ1-	EXCILE			
Software Support	VPP	18	52	VPP	EXGND	18	40	DO13
Windows <sup>®</sup> Platform	N/C	10	53	EYOND	DIN12	19	41	DO14
Available for Windows Vista32/XP/2000	11/0	15	00	EXCINE	DIN13	20	42	DO15
VB/VC++/BCB/Delphi/VB.NET are recommended programming	PEL0	20	54	PEL1	DIN14	21	43	EXGND
environment.	MEL0	21	55	MEL1	DIN15	22	11	EXCND
Customized API functions are possible	EXGND	22	56	EXGND	Divis	22		LXOND
	LTC/SD/PCS0/	23	57	LTC/SD/PCS1/				
MotionCreatorPro ™	CLR0			CLR1				
MotionCreatorPro™ assists the motion system developer to debug any cabling problem, and solve the difficulty of system	ORG0	24	58	ORG1				
configuration before programming.	N/C	25	59	EXGND				
Linux Platform	54, 100			EXCIL				
Redhat 9, kernel 2.4.x	PA+_ISO	26	60	EMG				
SUSE 10, kernel 2.6.13	PAISO	27	61	DIN0				
Fedora Core 5, kernel 2.6.15	PB+_ISO	28	62	DIN1				
Fedora Core 3, Kernel 2.6.9 Fedora Core 4, Kernel 2.6.1	PB- ISO	29	63	DIN2				
		30	64					
		00	04	DOUTO				
	CMP1	31	05	00010				
	EXGND	32	66	DOUT1				
	EXGND	33	67	EXGND				
	EX+24V	34	68	EX+24V				

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